

Infinitary pp-definability over the real numbers with convex relations

Sebastian Meyer

Institute of Algebra
TU Dresden

Workshop on General Algebra, June 2023



European Research Council
Established by the European Commission

ERC Synergy Grant POCOCOP (GA 101071674)

1 What are we talking about?

2 What is going on here?

3 Why is this interesting?

Definition

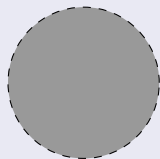
σ -structure X . The **infinitary primitive positive closure** (ipp-closure) is the smallest set of relations containing σ , closed under

- existentially quantification
- adding unused variables and
- finite **or infinite** conjunctions with finitely many free variables.

Examples

Take the open unit circle $B \subseteq \mathbb{R}^2$.

Definition (Circle)

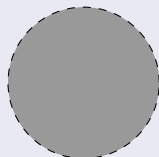


$$\{(x, y) \mid (x, y) \in B\} \in \mathbb{R}^2$$

Examples

Take the open unit circle $B \subseteq \mathbb{R}^2$.

Definition (Circle)



$$\{(x, y) \mid (x, y) \in B\} \in \mathbb{R}^2$$

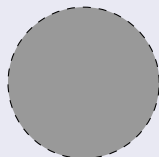
Definition (Line)

$$\{x \mid \exists y: (x, y) \in B\} \in \mathbb{R}$$

Examples

Take the open unit circle $B \subseteq \mathbb{R}^2$.

Definition (Circle)



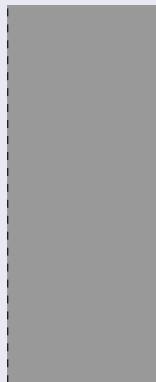
$$\{(x, y) \mid (x, y) \in B\} \in \mathbb{R}^2$$

Definition (Line)



$$\{x \mid \exists y: (x, y) \in B\} \in \mathbb{R}$$

Definition (Infinite Rectangle)



$$\{(x, y) \mid \exists z: (x, z) \in B\} \in \mathbb{R}^2$$

Examples

Take the open unit circle $B \subseteq \mathbb{R}^2$.

Definition (Square)



$$\{(x, y) \mid \exists a, b: (x, a) \in B \wedge (y, b) \in B\}$$

Question

Common relations

- addition $+$: $\{(x, y, z) \in \mathbb{R}^3 \mid x + y = z\}$.
- scalar multiplication $\cdot c \in \mathbb{R}$: $\{(x, y) \in \mathbb{R}^2 \mid cx = z\}$.
- constant $\{1\} \subseteq \mathbb{R}$.

Question

Common relations

- addition $+$: $\{(x, y, z) \in \mathbb{R}^3 \mid x + y = z\}$.
- scalar multiplication $\cdot c \in \mathbb{R}$: $\{(x, y) \in \mathbb{R}^2 \mid cx = z\}$.
- constant $\{1\} \subseteq \mathbb{R}$.

Question

Take the structure $(\mathbb{R}; +, \cdot c \mid c \in \mathbb{R}, 1, S)$ where S is a convex set, what is the ipp-closure?

Question

Common relations

- addition $+$: $\{(x, y, z) \in \mathbb{R}^3 \mid x + y = z\}$.
- scalar multiplication $\cdot c \in \mathbb{R}$: $\{(x, y) \in \mathbb{R}^2 \mid cx = z\}$.
- constant $\{1\} \subseteq \mathbb{R}$.

Question

Take the structure $(\mathbb{R}; +, \cdot c \mid c \in \mathbb{R}, 1, S)$ where S is a convex set, what is the ipp-closure?

Answer

There are 6 possible closures.

They will be described later.

Question

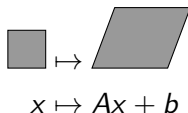
Take the structure $(\mathbb{R}; +, \cdot c \mid c \in \mathbb{R}, 1, S)$ where S is a convex set, what is the *ipp*-closure?

- Every constant is definable.

Question

Take the structure $(\mathbb{R}; +, \cdot \mid c \in \mathbb{R}, 1, S)$ where S is a convex set, what is the *ipp-closure*?

- Every constant is definable.
- For an affine transformation



and a definable set Z , also its image and preimage

$$\{y \mid \exists x: x \in Z \wedge Ax + b = y\}$$

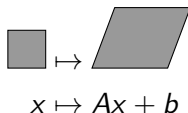
$$\{x \mid \exists y: Ax + b = y \wedge y \in Z\}$$

are definable.

Question

Take the structure $(\mathbb{R}; +, \cdot \mid c \in \mathbb{R}, 1, S)$ where S is a convex set, what is the *ipp-closure*?

- Every constant is definable.
- For an affine transformation



and a definable set Z , also its image and preimage

$$\{y \mid \exists x: x \in Z \wedge Ax + b = y\}$$

$$\{x \mid \exists y: Ax + b = y \wedge y \in Z\}$$

are definable.

- Every affine set is definable.

- We can reformulate the question:

Question

What is the smallest set containing S , constants, affine projections, affine preimages and arbitrary intersections?

- We can reformulate the question:

Question

What is the smallest set containing S , constants, affine projections, affine preimages and arbitrary intersections?

- Every ipp-definable set is convex.

- We can reformulate the question:

Question


What is the smallest set containing S , constants, affine projections, affine preimages and arbitrary intersections?

- Every ipp-definable set is convex.
- If S is affine, then every ipp-definable set is affine.

- We can reformulate the question:

Question

What is the smallest set containing S , constants, affine projections, affine preimages and arbitrary intersections?

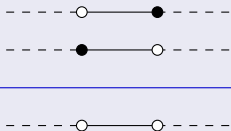
- Every ipp-definable set is convex.
- If S is affine, then every ipp-definable set is affine.
- If S is a ray () then every closed convex set is definable by the Hahn-Banach-Theorem.

First Classifications

Table: Classification of convex sets with dimension at most 1

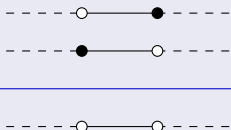
	empty set	\emptyset
•	single point	$\{0\}$
-----○-----○-----	open interval	$(0, 1)$
-----●-----○-----	half open interval	$[0, 1)$
-----●-----●-----	compact interval	$[0, 1]$
-----○-----	open ray	$(0, \infty)$
-----●-----	closed ray	$[0, \infty)$
-----	real line	$(-\infty, \infty)$

Definition (Cutting edges)

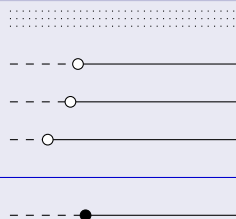


First Classifications

Definition (Cutting edges)

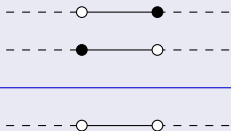


Definition (Infinite cut)

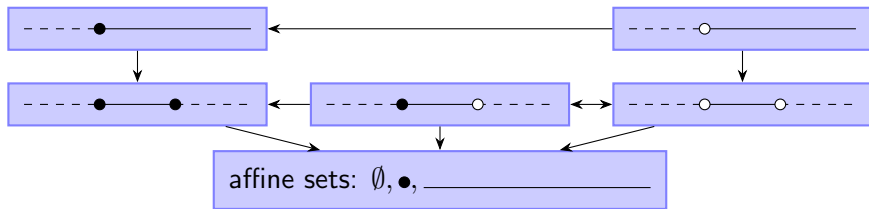
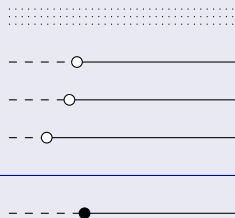


First Classifications

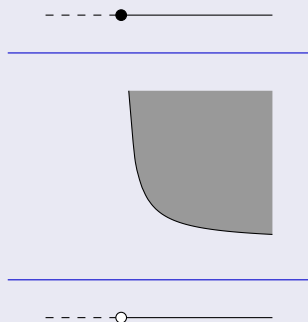
Definition (Cutting edges)



Definition (Infinite cut)



Definition (Obtaining non-closed sets)

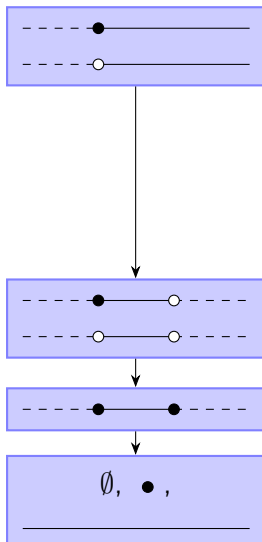


The closed set

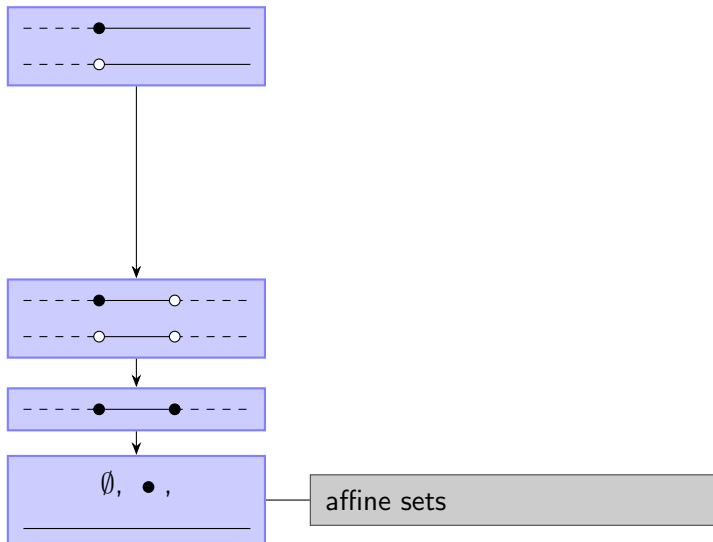
$$\{(x, y) \mid x, y \geq 0 \wedge xy \geq 1\}$$

is ipp-definable from the closed ray. Its projection is the open ray.

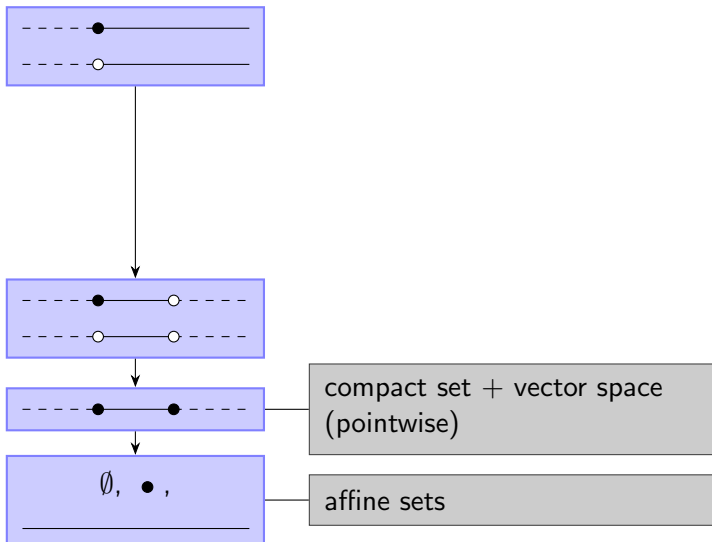
Classification result



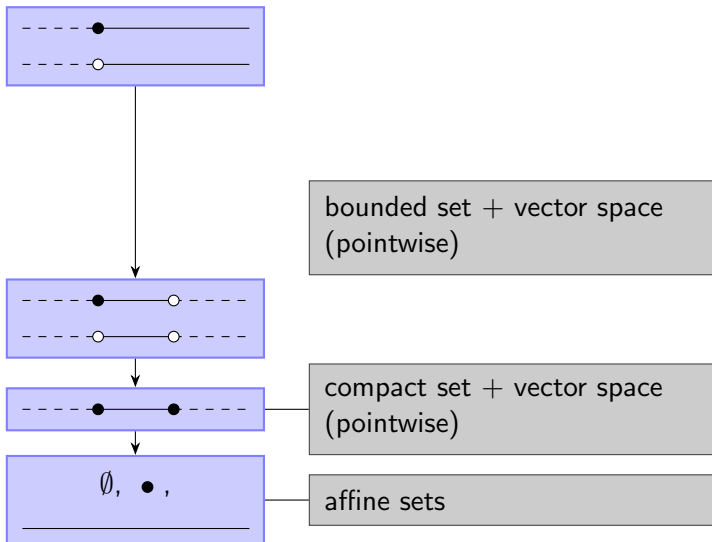
Classification result



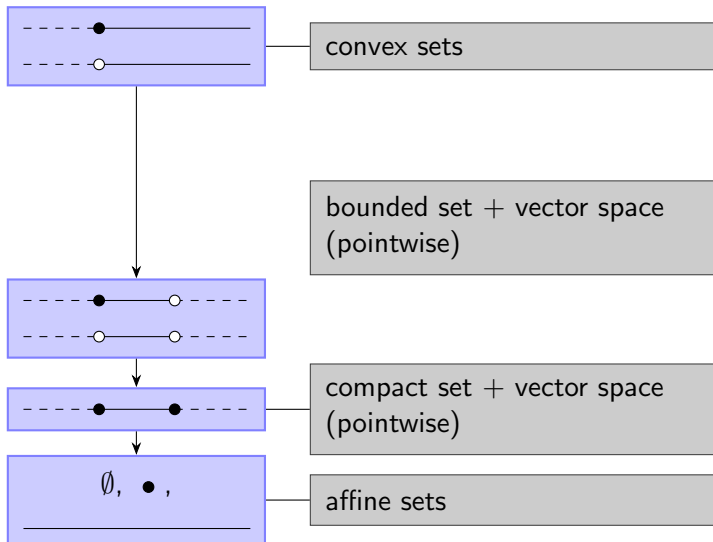
Classification result



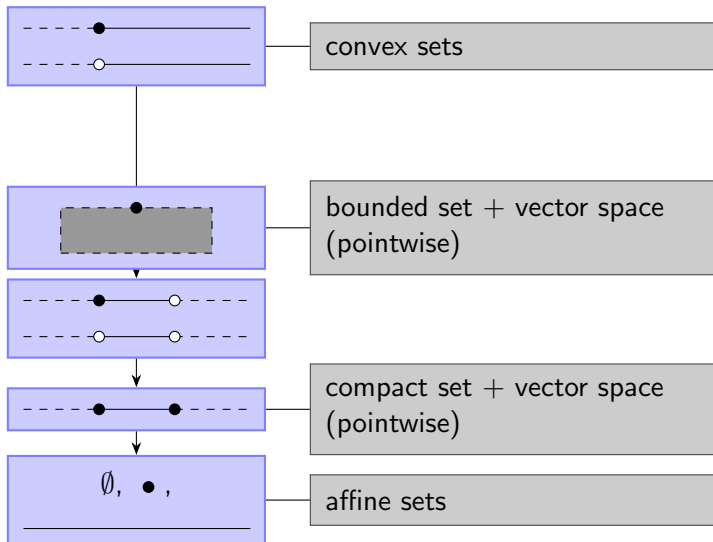
Classification result



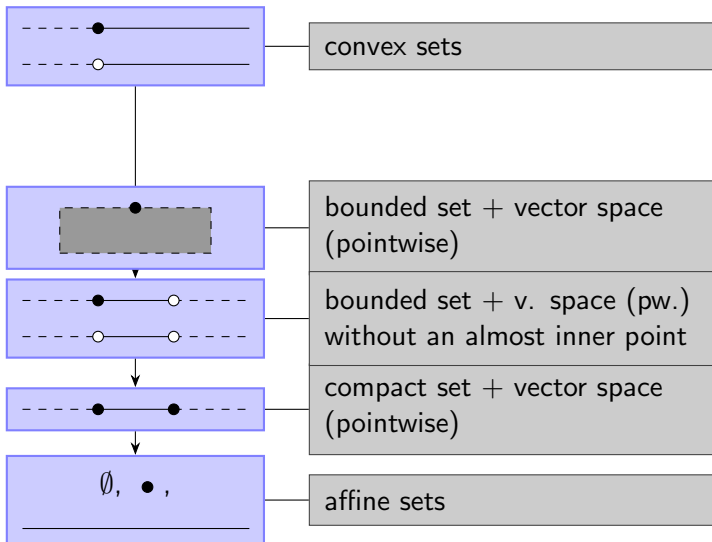
Classification result



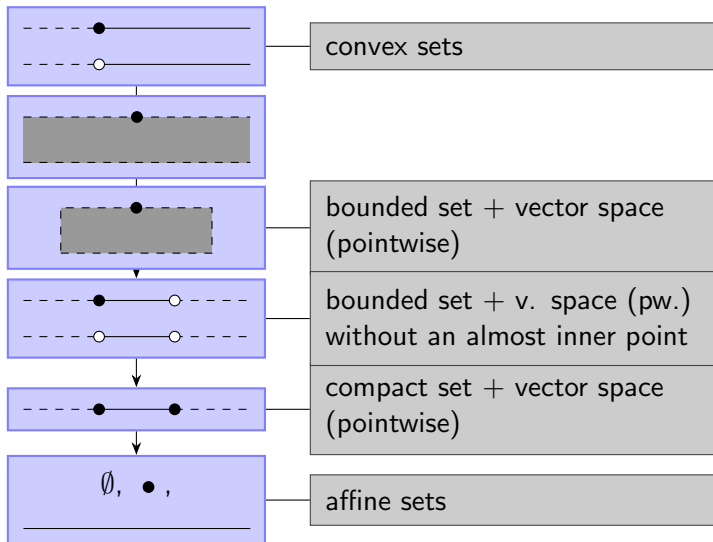
Classification result



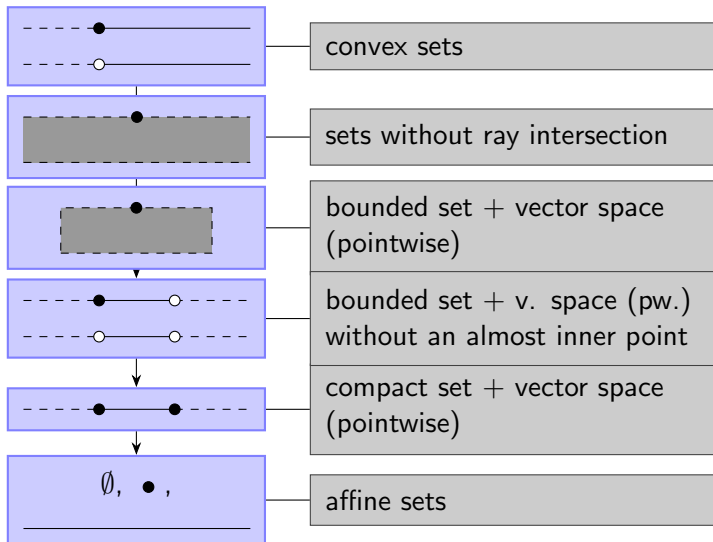
Classification result



Classification result



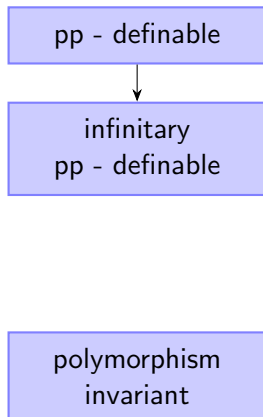
Classification result



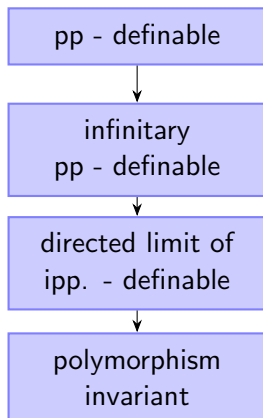
pp - definable

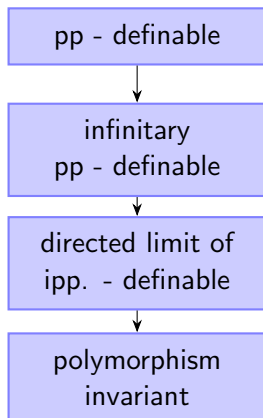
polymorphism
invariant

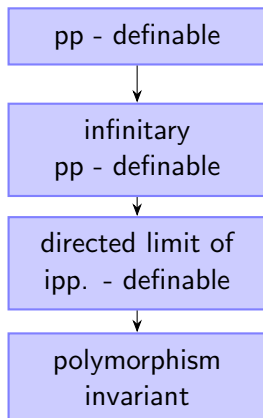
Applications



Applications



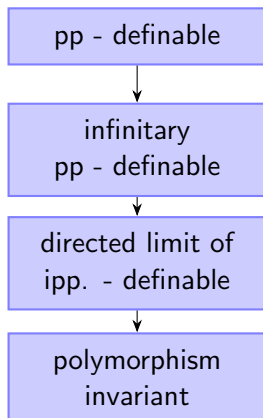




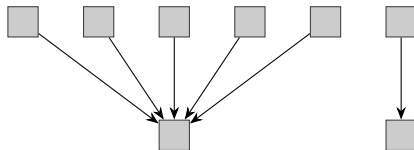
infinitely many equivalence classes



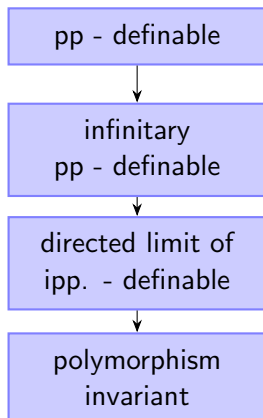
Applications



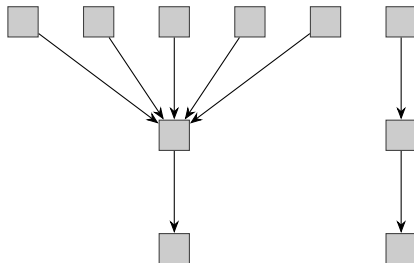
infinitely many equivalence classes



Applications



infinitely many equivalence classes



Definition

A map

$$f : \mathbb{R}^n \rightarrow \mathbb{R}$$
$$(x_1, \dots, x_n) \mapsto \lambda_1 x_1 + \dots + \lambda_n x_n$$

is called

- **linear combination** if $\lambda_1 + \dots + \lambda_n = 1$ and
- **convex combination** if additionally $\lambda_1, \dots, \lambda_n \geq 0$.

Definition

A map

$$f : \mathbb{R}^n \rightarrow \mathbb{R}$$
$$(x_1, \dots, x_n) \mapsto \lambda_1 x_1 + \dots + \lambda_n x_n$$

is called

- **linear combination** if $\lambda_1 + \dots + \lambda_n = 1$ and
- **convex combination** if additionally $\lambda_1, \dots, \lambda_n \geq 0$.

Corollary

There is no locally closed clone between the clone of all linear combinations and the clone of all convex combinations on \mathbb{R} .

Thank you for your attention

Funding statement: Funded by the European Union (ERC, POCOCOP, 101071674).

Views and opinions expressed are however those of the author(s) only and do not necessarily reflect those of the European Union or the European Research Council Executive Agency. Neither the European Union nor the granting authority can be held responsible for them.